

SIEMENS



BACnet LCM-OAVS

VAV Room Pressurization with
HW Reheat, Slow Damper
Supply and Venturi Exhaust,
Application 6724

Application Note

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Overview

Application 6724 controls pressurization, ventilation, and room temperature in a laboratory room served by one single-duct supply terminal with a reheat coil, one general exhaust terminal, and up to six fume hoods (multiple fume hood flow signals must be averaged using a Fume Hood Flow Module (FFM)). Pressurization is controlled by maintaining a selected difference between supply and exhaust airflows.

This version of the LCM uses conventional supply and exhaust actuation (rather than high speed actuation). Therefore, it should be used only where rapid room response to fume hood volume changes is not required. Fume hoods used in conjunction with these applications should be constant volume or slow actuation.



NOTE:

Application 6724 can be set up to operate without a supply box, or without a general exhaust box. See the *Application Notes* section for more information.

Application 6724 uses floating control electronic actuators for the supply control and a 0 to 10 Vdc signal to drive a Venturi Air valve for exhaust control. A standard 0 to 10 Vdc actuator is used for the hot water valve.

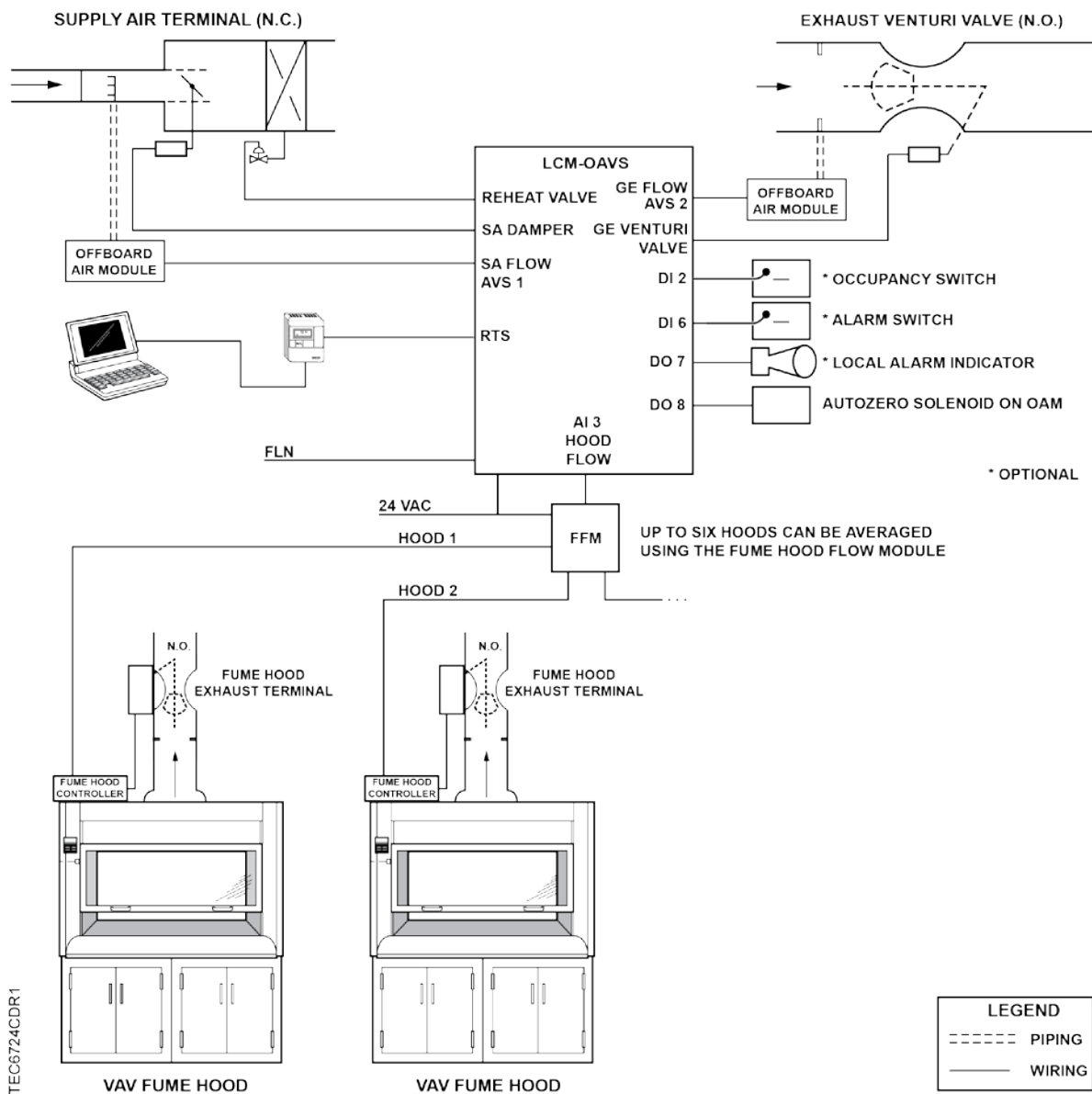


NOTE:

The LCM controls pressure, ventilation, and temperature. When these functions conflict, the priorities are:

- Pressurization
 - Ventilation (supply minimum may be overridden to maintain negative pressurization)
 - Temperature
-

Temperature control is determined by input from the room temperature sensor.



Ventilation and Pressurization Control Drawing.

BACnet

The controller communicates using BACnet MS/TP protocol for open communications on BACnet MS/TP networks.

Product	Supported BIBBs	BIBB Name
BTEC	DS-RP-B B	Data Sharing-Read Property-B
	DS-RPM-B	Data Sharing-Read Property Multiple-B
	DS-WP-B	Data Sharing-Write Property-B
	DM-DDB-B	Device Management-Dynamic Device Binding-B
	DM-DOB-B	Device Management-Dynamic Object Binding-B

Product	Supported BIBBs	BIBB Name
	DM-DCC-B	Device Management-Device Communication Control-B
	DM-RD-B	Device Management-Reinitialize Device-B
	DM-BR-B	Device Management-Backup and Restore-B
	DM-OCD-B	Device Management-Object Creation and Deletion-B

Hardware Inputs

Analog

- Air velocity sensor (s) – (one or two depending on setup)
- Fume hood controller input or FFM
- Room temperature sensor

Digital

- Occupancy button (option on room temperature sensor)
- Occupancy switch (optional)
- Alarm switch (optional)

Hardware Outputs

Analog

- Reheat valve
- General exhaust Venturi Air Valve

Digital

- Autozero Solenoid in Offboard Air Module (DO8)
- Alarm (optional)
- Supply damper (two DOs)

Ordering Notes

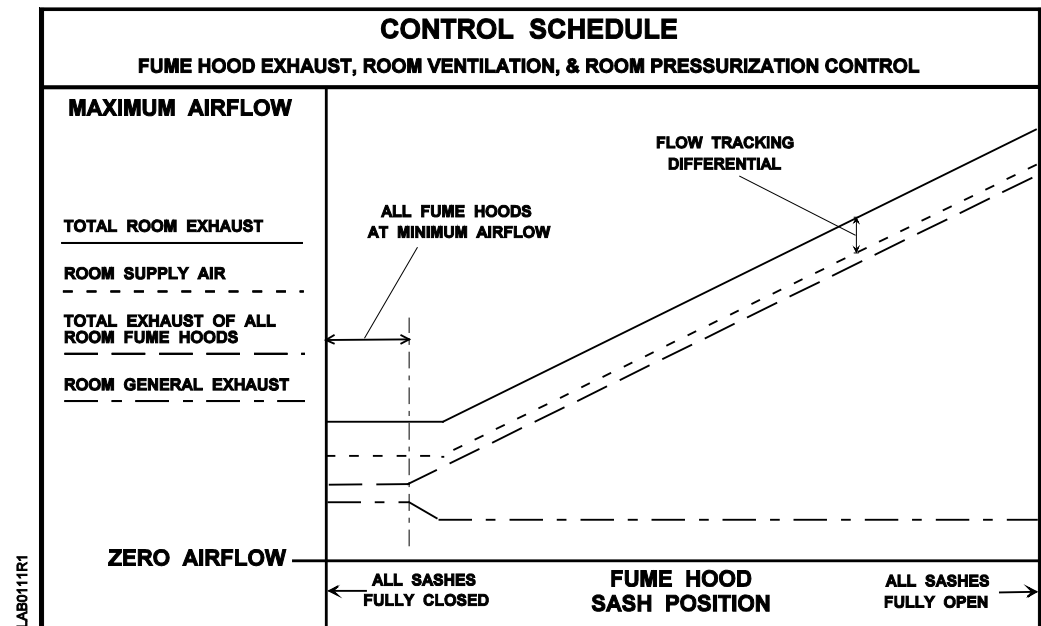
570-805P	BACnet LCM-OAVS Variable Air Volume Room Pressurization with HW Reheat and Slow Supply Damper Actuation, Slow Venturi Exhaust Actuation Requires Offboard Air Module(s) – order and ship separately
550-819B	Offboard Air Module (OAM) – order and ship separately

Sequence of Operation

The following paragraphs present the sequence of operation for BACnet LCM-OAVS VAV Room Pressurization with HW Reheat, Slow Supply Damper Actuation and Slow Exhaust Venturi Air Valve.

Pressurization Control

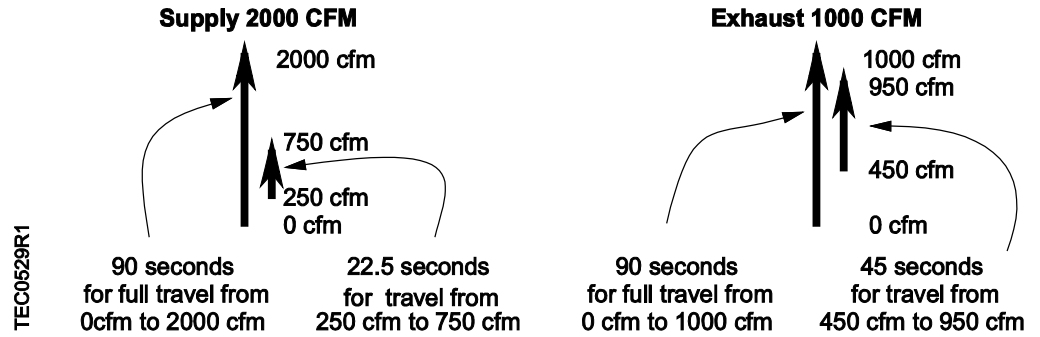
The goal of pressurization control is to maintain a fixed difference between the volumes of total supply air and total exhaust air (see the following Figure). The controller selects supply and exhaust setpoints to balance flows while meeting supply air requirements, and the supply and exhaust flows are individually controlled by respective feed-forward table statements and feedback loops in order to meet the setpoints.



Optional Rate Limiting of Actuators

Under specific circumstances, such as when operating open loop with setpoint tracking and differently sized supply and exhaust, it may be necessary to adjust the actuator travel rates to improve pressurization control.

The example below illustrates when a rate limit might be needed, such as when equal travel times for the supply and exhaust actuators yield large differences in their respective flow rates.



To deal with the possibility of unequal flow rate changes, the application includes two new points which allow field adjustment to slow down actuators. **SUP MAX RATE** is used to effectively limit the speed of the supply actuator; **GEX MAX RATE** is used to effectively limit the speed of the exhaust actuator.

SUP MAX RATE and **GEX MAX RATE** should be changed to values other than 0 only after a thorough analysis has been made of the job specific scenarios. For example, slowing down a given supply actuator to match a general exhaust actuator may actually be detrimental overall if the installation includes faster acting fume hoods.

To limit the rate of the actuator (supply or exhaust depending on your setup) that controls the larger and faster changing flow rate, do the following: Take the max flow cfm value of the box you want to slow down and divide by its actuator runtime in seconds, then divide the result by 4 and round to the nearest integer. Enter this final value in either **SUP MAX RATE** or **GEX MAX RATE** depending on which box you want to slow down.

Here is the formula in its simplest terms, where “max cfm” represents the maximum flow value of the box that you want to slow down:

$$(\text{max cfm} \div \text{runtime}) \div 4 = \text{SUP (or GEX) MAX RATE}$$



NOTE:

This value is a good starting point. If necessary, you can raise it (must be an integer) to speed up the rate of flow change, or lower it to further slow down the rate of flow change, while observing the overall stability of your setup.

To accommodate the largest variety of room configurations and pressurization needs, the rate limit will **ONLY** be applied when the actuator is moving in the direction that if left uncontrolled could cause pressurization reversal. See table below.

	SUPPLY	GENERAL EXHAUST
OCC DIF STPT (or UOC DIF STPT) <0 Maintain positive pressurization	The SUP MAX RATE is applied to supply closing but not to supply opening.	The GEX MAX RATE is applied to general exhaust opening but not to general exhaust closing.
OCC DIF STPT (or UOC DIF STPT) >=0 Maintain negative pressurization	The SUP MAX RATE is applied to supply opening but not to supply closing.	The GEX MAX RATE is applied to general exhaust closing but not to general exhaust opening.

Room Airflow Balance

The difference between total supply flow and total exhaust flow is the room airflow balance as shown in these calculations:

$$\text{VOL DIFFRNC} = \text{TOTL EXHAUST} - \text{TOTL SUPPLY}$$

-or-

$$\text{VOL DIFFRNC} = (\text{HOOD VOL} + \text{GEX AIR VOL} + \text{OTHER EXH}) - (\text{SUP AIR VOL} + \text{OTHER SUP})$$

The controller uses these calculations to maintain VOL DIFFRNC at the VOL DIF STPT.



NOTE:

VOL DIFFRNC and VOL DIF STPT are positive numbers in a room that is negatively pressurized and negative in a positively pressurized room.

Application 6724 has the ability to maintain a different volume differential setpoint during occupied mode than during unoccupied mode. When OCC.UNOCC = OCC, VOL DIF STPT = OCC DIF STPT. When OCC.UNOCC = UNOCC, VOL DIF STPT = UOC DIF STPT.

Occupancy

The controller keeps track of the occupancy status of the room and uses that information for the following purposes:

- To select minimum and maximum flow rates for each air terminal.
- To select whether the controller is operating in the VAV or CV mode.
- To determine whether the controller is using Supply Tracks Exhaust (STE) or Exhaust Tracks Supply (ETS) flow tracking.
- To determine the value of VOL DIF STPT.
- To calculate the airflow level that triggers the ventilation alarm.

Occupancy status also affects the airflow level that triggers the ventilation alarm. The occupancy status of the room is indicated by OCC.UNOCC. A digital room thermostat can read OCC.UNOCC and display its value. This point cannot be overridden.

If the occupancy status of the room is set manually, it is necessary to work through the following command options.

The controller works in the occupied mode whenever **one or more** of the following occupancy signals indicates occupancy:

- Commands from a field panel, NET OCC CMD
- Dry contact switch in the room, OCC SWIT DI2
- Push button on the thermostat, OCC BUTTON

If **all** of these occupancy signals indicate vacancy, the controller works in the unoccupied mode.

NET OCC CMD – The NET OCC CMD may be set from a field panel by OCC and UNOCC commands to the LCTLR point. The commands may come from a time-of-day schedule, a PPCL program, or operator commands. These commands work on the LCTLR without unbundling.



NOTE:

The displayed OCC/UNOCC status of the LCTLR point does not always match the occupancy status of the controller. To get an actual indication of occupancy status, OCC.UNOCC must be used.

If network commands are not required and occupancy is to be set by sources in the room, set NET OCC CMD to UNOCC. If set to OCC, the controller will stay in occupied mode.

OCC ENA is an analog point whose value determines whether or not OCC BUTN DI1, or OCC SWIT DI2, is enabled.

The following table shows what is enabled when OCC ENA is at a particular value.

OCC ENA Values.	
OCC ENA (value)	Description
0 (default)	Both OCC BUTN DI1 and OCC SWIT DI2 are disabled.
1	Only OCC BUTN DI1 is enabled.
2	Only OCC SWIT DI2 is enabled.



NOTE:

OCC ENA does not allow both OCC BUTN DI1 and OCC SWIT DI2 to be enabled at the same time. If OCC ENA is set greater than 2, it will default to 0.

OCC SWIT DI2 – The occupancy switch (dry contact switch in the room) can be any device that closes the switch when the room is occupied (occupancy sensor, extra contact on light switch, etc.). The controller uses this input for occupancy if the setup point OCC ENA is set to 2. Otherwise, OCC SWIT DI2 does not affect occupancy.

OCC BUTTON – Some Siemens Industry thermostats include a momentary switch with a push button. The controller can use this button as a source of occupancy commands if the setup point, OCC ENA, is set to 1.

When the room sensor button is pushed, the controller interprets this as a request to change the occupancy status of the room. If the room is unoccupied, it changes to occupied. If it is occupied, it *may* switch to unoccupied, depending on the states of the other occupancy sources. The current request status of the room sensor button is indicated by BUTTON CMD. This point is used to investigate the room sensor button's effect on the occupancy status of a room.

OCC BUTTON does not provide that information because it is connected to a momentary switch.

Active Flow Minimums and Maximums

When OCC.UNOCC equals OCC:

- The active supply airflow minimum equals OCC SUP MIN.
- The active supply airflow maximum equals OCC SUP MAX.
- The active general exhaust airflow minimum equals OCC GEX MIN.
- The active general exhaust airflow maximum equals OCC GEN MAX.

When OCC.UNOCC equals UNOCC:

- The active supply airflow minimum equals UOC SUP MIN.
- The active supply airflow maximum equals UOC SUP MAX.
- The active general exhaust airflow minimum equals UOC GEX MIN.
- The active general exhaust airflow maximum equals UOC GEN MAX.

VAV vs. CV Control

In Application 6724, VAV means that the supply airflow can be varied to provide cooling. CV means the supply airflow is not a source of cooling. However, the supply and general exhaust can still change in CV mode to keep the volume differential setpoint constant. This may be necessary if HOOD VOL is varying. Application 6724 can do either Variable Air Volume control (VAV) or Constant Air Volume Control (CV). It can also change the type of air volume control based on which mode it is operating in (OCC or UNOCC).

- When OCC.UNOCC equals **OCC**, Application 6724 will perform VAV control provided that VOLUME STATE equals **1** or **3**. It will perform constant volume (CV) control provided that VOLUME STATE equals **0** or **2**.
- When OCC.UNOCC equals **UNOCC**, Application 6724 will perform VAV control provided that VOLUME STATE equals **2** or **3**. It will perform constant volume control provided that VOLUME STATE equals **0** or **1**.

Depending on how VOLUME STATE is configured, Application 6724 can operate as either a variable air volume (VAV) LCM or a constant volume (CV) LCM. Also, these operational modes can vary between the occupied and unoccupied periods, if desired.

The following table shows what the application does when VOLUME STATE is at a particular value.

VOLUME STATE Values.	
VOLUME STATE (value)	Description
0	Always Constant Volume.
1 (default)	VAV during occupancy, Constant Volume during unoccupied period.
2	Constant Volume during occupancy, VAV during unoccupied period.
3	Always VAV.



NOTE:

If VOLUME STATE is set greater than 3, it will default to 0.

Fume Hood Flow Input

This version of the LCM uses conventional supply and exhaust actuation (rather than high speed actuation). Therefore, it should be used only where rapid room response to fume hood volume changes is not required. Fume hoods used in conjunction with these applications should be constant volume or slow actuation.

A signal of 1 to 10 Vdc at AI 3 represents the volume of air that is exhausted through the fume hood(s). By using a Fume Hood Flow Module (FFM), you can connect up to six fume hoods to AI 3. Multiple fume hood flows must be averaged using a Fume Hood Flow Module. The resulting airflow is displayed in point HOOD VOL.

MAX HOOD VOL is set during start-up to indicate the flow in cubic feet per minute (cfm) that corresponds to an input signal of 10 Vdc. A signal of 1 Vdc indicates 0 cfm. If the signal drops below 1 Vdc, TOTL EXHAUST will fail.

MINHOODVOLTS is set during start-up to indicate the voltage input that represents the lower limit of the airflow range (such as 0 Vdc or 1 Vdc).

- If MINHOODVOLTS is set to 1Vdc or greater, and the actual voltage input drops below .4Vdc, a hood volume alarm is generated. The alarm will return to normal when the voltage increases above .6Vdc
- If the MINHOODVOLTS is set less than 1 Vdc (such as to 0 Vdc), then there is no alarm generated when crossing the .4 Vdc threshold. This disabling of alarm allows the use of input devices that use the full range of 0-10 Vdc.



NOTE:

If desired, the LCM can be used without any fume hoods attached. In this case, MAX HOOD VOL should be set to 0 cfm to disable the alarming that would occur if the fume hood flow input drops below 1 Vdc.

Flow Tracking – Supply Tracks Exhaust vs. Exhaust Tracks Supply

The Supply Tracks Exhaust (STE) and Exhaust Tracks Supply (ETS) feature is configured by setting TRACK MODE to STE or ETS to help the controller meet the pressurization needs of the controlled space, such as for negative or positive pressure. TRACK METHOD is used to determine what is being tracked – a flow value or a setpoint value. Regardless of the mode (STE or ETS) in which the controller is operating, the application will change the value of TRACK METHOD from STPT to FLOW (that is, from setpoint tracking to flow tracking) if necessary to maintain proper pressurization. This is important in situations where a room may lack sufficient supply or general exhaust capacity. The following paragraphs explain this in greater detail.

Supply Tracks Exhaust mode is useful when trying to maintain negative pressurization. During Supply Tracks Exhaust, the supply air volume "tracks" or follows the exhaust air volume. If the exhaust air is "broken" (for instance, if the general exhaust airflow control device is stuck open or stuck closed), the supply air volume will be adjusted so that VOL DIF STPT is maintained as much as possible. (The supply air volume cannot go lower than zero and the application will not allow it to go higher than OCC SUP MAX during occupied periods, or UOC SUP MAX during unoccupied periods.)

Exhaust Tracks Supply mode is useful when trying to maintain positive pressurization. During Exhaust Tracks Supply, the general exhaust air volume "tracks" or follows the supply air volume. If the supply air is "broken" (for instance, if the supply airflow control device is stuck open or stuck closed), the general exhaust air volume will be adjusted so that VOL DIF STPT is maintained as much as possible. (The general exhaust air volume cannot go lower than zero and the application will not allow it to go higher than OCC GEX MAX during occupied periods, or UOC GEX MAX during unoccupied periods.)

The selected track mode is not affected by occupancy status (OCC or UNOCC), and is set by the value of TRACK MODE.

TRACK MODE Values.	
	TRACK MODE
0 default	Always STE (Supply Tracks Exhaust).
1	STE during occupancy, ETS during the unoccupied period.
2	ETS during occupancy, STE during the unoccupied period.
3	Always ETS (Exhaust Tracks Supply).

**NOTE:**

If TRACK MODE is set greater than 3, it will default to 0.

TRACK METHOD

A point associated with TRACK MODE is TRACK METHOD. TRACK MODE determines which airflow (supply or general exhaust) gets tracked and which airflow does the tracking. TRACK METHOD determines how tracking is accomplished.

- If TRACK MODE is set to ETS and TRACK METHOD is set for FLOW tracking, the general exhaust flow setpoint is calculated according to the measured value, SUP AIR VOL.
- If TRACK METHOD is set for STPT tracking, the general exhaust flow setpoint is calculated according to the supply flow setpoint. However, this module changes over to FLOW tracking mode if the supply is unable to reach the setpoint.

This feature prevents the incorrect pressurization of rooms that lack the required supply capacity. The changeover is based on the error of the supply flow loop. If the error is greater than FAIL LIMIT, and stays that way for a time longer than FAIL TIME, then the module changes from STPT tracking to FLOW tracking. It stays in that mode until the error comes back to zero, then switches back to the STPT tracking mode.

- If TRACK MODE is set to STE and TRACK METHOD is set for FLOW tracking, the supply flow setpoint is calculated according to the measured value, GEX AIR VOL.
- If TRACK METHOD is set for STPT tracking, the supply flow setpoint is calculated according to the general exhaust flow setpoint. However, this module changes over to FLOW tracking mode if the general exhaust is unable to reach the setpoint.

This feature prevents the incorrect pressurization of rooms that lack the required general exhaust capacity. The changeover is based on the error of the general exhaust flow loop. If the error is greater than FAIL LIMIT, and stays that way for a time longer than FAIL TIME, then the module changes from STPT tracking to FLOW tracking. It stays in that mode until the error comes back to zero, then switches back to the STPT tracking mode.

Calculating Exhaust Flow Setpoint

When **Supply Tracks Exhaust (STE)** flow tracking is being used, the general exhaust airflow setpoint is calculated as follows:

- During VAV operation, the controller calculates GEX FLO STPT by looking at the value of TEMP CTL VOL and determining the general exhaust flow needed to pressurize the room. If TEMP CTL VOL is less than the active supply minimum, the controller ignores TEMP CTL VOL and calculates GEX FLO STPT based on the value of the active supply flow minimum.
- During CV operation, the controller ignores TEMP CTL VOL. Instead, it calculates GEX FLO STPT based on the value of the active supply flow minimum and the amount of general exhaust airflow needed to pressurize the room.



NOTE:

When Supply Tracks Exhaust (STE) flow tracking is being used, the controller does not allow GEX FLO STPT (or the actual general exhaust flow) to rise above the active general exhaust airflow maximum. **However, the general exhaust airflow minimum can be overridden in situations where doing so is necessary to maintain desired room pressurization.**

When **Exhaust Tracks Supply (ETS)** flow tracking is being used, the general exhaust airflow setpoint is calculated the same during both VAV and CV operation, as follows:

To calculate GEX FLO STPT, the controller determines the general exhaust airflow value that pressurizes the room based on the values of VOL DIF STPT, OTHER EXH, OTHER SUP and either SUP FLO STPT or SUP AIR VOL depending on the value of TRACK METHOD. GEX FLO STPT may not exceed the active general exhaust airflow maximum, but the currently active general exhaust airflow minimum (OCC GEX MIN or UOC GEX MIN) will be overridden if necessary to maintain the desired room pressurization.

Calculating Supply Flow Setpoint

When **Supply Tracks Exhaust (STE)** flow tracking is being used, the supply airflow setpoint is calculated the same during both VAV and CV operation, as follows:

To calculate SUP FLO STPT, the controller determines the supply flow value that pressurizes the room based on the values of VOL DIF STPT, OTHER EXH, OTHER SUP, and either GEX FLO STPT or GEX AIR VOL depending on the value of TRACK METHOD. SUP FLO STPT may not exceed the currently active supply airflow maximum.

When **Exhaust Tracks Supply (ETS)** flow tracking is being used, the supply airflow setpoint is calculated as follows:

- During VAV operation, the controller calculates SUP FLO STPT by looking at the value of TEMP CTL VOL and determining the supply flow needed to pressurize the room. If TEMP CTL VOL is less than the active supply minimum, the controller ignores TEMP CTL VOL and calculates SUP FLO STPT based on the value of the active supply flow minimum.

- During CV operation, the controller ignores TEMP CTL VOL. Instead, it calculates SUP FLO STPT based on the value of the active supply flow minimum and the amount of supply airflow needed to pressurize the room.



NOTE:

Regardless of the flow tracking method (STE or ETS) being used, the controller does not let the actual supply airflow rise above the currently active supply airflow maximum. **However, the currently active supply airflow minimum (OCC SUP MIN or UOC SUP MIN) will be overridden if necessary to achieve desired pressurization.**

External Flow Values

Airflows not connected to the LCM must be taken into consideration when pressurizing the room, including snorkels, canopies, and other supplies, such as offices within the lab space controlled by constant volume controllers. Since these inputs are not connected to the LCM, the combination of their values must be entered into OTHER SUP and OTHER EXH so the LCM can properly control the lab space.



NOTE:

If these airflow values change slowly or predictably (for example, VAV temperature control and/or occ/unoc differences), steps can be taken using PPCL to have the changes sent over the network to update OTHER EXH and OTHER SUP with the new values

Ventilation – VAV Mode

During VAV operation, the ventilation works as follows:

The occupied supply minimum, OCC SUP MIN is used to ensure that the room receives enough supply air for proper ventilation during the occupied mode. UOC SUP MIN is used to ensure that the room receives enough supply air for proper ventilation during the unoccupied mode. If necessary, the application raises the general exhaust flow to keep the supply flow from dropping below the minimum. See *Calculating Exhaust Flow Setpoint* for more information.



NOTE:

Since Application 6724 places a higher priority on pressurization than it does on ventilation, the currently active supply minimum (OCC SUP MIN or UNOCC SUP MIN) may be overridden to maintain negative pressurization.

Ventilation Setback in VAV Mode

Ventilation setback allows the minimum and maximum flows (air change rate) for each VAV terminal to vary based on occupancy mode (OCC.UNOCC). This allows several options for reducing the ventilation for unoccupied periods, including:

- Lowering the minimum supply flow, which allows a lower air change rate, but maintains cooling control.
- Lowering the maximum flow, which limits the air change rate and reduces cooling capacity.
- Closing the general exhaust, which lowers airflow and disables cooling completely.

Ventilation – Constant Volume Mode

During Constant Volume (CV) operation, the active supply airflow minimum is used to ensure that the room always receives enough supply air for proper ventilation. If necessary, the application raises the general exhaust flow to keep the supply flow from dropping below the minimum. See *Calculating Exhaust Flow Setpoint* for more information.

In CV mode the active supply minimum is the setpoint. The active supply airflow minimum is used to ensure that the room always receives enough supply air for proper ventilation.

During CV operation, the air volume out of the supply box will equal the active supply airflow minimum as long as this is sufficient to maintain proper room pressurization.



NOTE:

Regardless of the operation—VAV or CV temperature control—airflow out of both the supply and general exhaust box will vary as needed in order to maintain proper room pressurization whenever HOOD VOL changes.

AVS Calibration

Calibration of the air velocity transducer(s) is periodically required to maintain accurate air velocity readings. Depending on the value of CAL SETUP, calibration takes place either at fixed time intervals or whenever the application goes into unoccupied mode. When calibration is in progress, CAL AIR equals YES. After calibration, CAL AIR returns to NO.

Application 6724 uses Autozero Modules connected to AUTOZERO DO8. This means that the supply and general exhaust flow control devices do not close during calibration of the transducers.



NOTE:

The LCM does not monitor Fume Hood flow changes during AVS calibration.

Airflow Control

The supply flow is controlled with a feedback loop to operate the floating control damper motor so that the measured air velocity is maintained at setpoint. To enhance stable flow control, an advanced algorithm is used to calculate a controllable setpoint as the value approaches zero cfm (lps). This feedback loops works as follows:

When the flow is slightly below the setpoint, the LCM opens the floating control damper motor slowly, more and more until the airflow reaches the setpoint, at which time the air damper's position remains constant. If the flow is far below the setpoint, the LCM opens the floating control damper rapidly, more and more until the airflow reaches the setpoint, at which time the air damper's position remains constant. The feedback gain SUP P GAIN is adjusted to tune the flow loop. The sample loop time for the flow loops is fixed at 2.0 seconds. I and D gain are inherent in the system and do not need adjustment.

The application has logic in it that prevents the feedback loops from trying to move the damper motors faster than they can actually go. This helps minimize airflow overshoots and undershoots whenever there is a large airflow setpoint change. The greatest amount of position change that the supply damper motor will be allowed to undergo during each execution of the supply airflow feedback loop is $\pm (100\% * \text{flow loop execution speed}) / \text{MTR1 TIMING}$. The flow loop execution speed is fixed in this application at 2.0 seconds.



NOTES:

1. Open the door to the controlled space and set VOL DIF STPT must be set to zero while the flow loops are being tuned.
 2. The damper motor command point for supply is SUP DMP CMD The supply damper motor may be set up for normally open or normally closed operation depending on the value of MTR SETUP. See the *Damper Configuration section of the Start-up document* for more information on motor setup.
-

Damper Status

When an Autozero solenoid from an Offboard Air Module is wired to D0 8, the physical damper position may vary from what the application's position point is indicating. A Damper Status firmware algorithm will detect and correct situations where airflow velocity is greater than 200 fpm and the following is true:

- SUP DMP POS = 100% and SUP VOL < SUP STPT

OR

- SUP DMP POS = 0% and SUP VOL > SUP STPT

When initiated, the firmware module sets DMPR STATUS from CAL to RECAL and decrements/increments the damper position (in a reiterative sequence up to four cycles in length) until sensed airflow matches setpoint.



NOTE:

It is important to realize that while the Damper Status module runs, the damper position point (SUP DMP POS will change in value but the flow point (SUP VOL) might not.

To change DMPR STATUS from RECAL back to CAL, set DMPR STATUS to CAL and then release it. (A status of RECAL will not prevent the recalibration sequence from running if needed.)

Venturi Operational Modes

The general exhaust Venturi Air Valve can operate in one of three modes:

- Mode 1 – Operates with both a PID loop and a Venturi table.
This mode provides the best control and would be the most commonly used mode for these applications. In this mode, the embedded Venturi table statements works together with a PID feedback loop to operate the Venturi air valve so that the measured air velocity is maintained at setpoint. The following several sections describe this mode.
- Mode 2 - Operates with a PID loop but no Venturi table.
In this mode, the controller operates with PID control based on a flow sensor input, but the Venturi table is not used. See the PID Only Mode section later in this document for specific information on this mode.

- **Mode 3 - Operates with Venturi table but no PID loop**
In this mode, the controller operates open loop (without a flow sensor). There is no PID control. Positioning of the actuator is based solely on a Venturi table consisting of command voltages and their resultant corresponding airflows. See the Open Loop Mode section later in this document for specific information on how this mode differs from the normal mode 1 above.

Feedback Loop Operation

When the flow is slightly below the setpoint, the LCM opens the Venturi Air Valve slowly, more and more until the airflow reaches the setpoint, at which time the air valve's position remains constant. If the flow is far below the setpoint, the LCM opens the Venturi Air Valve rapidly, and rapidly increases until the airflow reaches the setpoint, at which time the air valve's position remains constant. The feedback gain GEX P GAIN is adjusted to tune the flow loop. The sample loop time for the flow loops is fixed at 2 seconds. I and D gain are inherent in the system and do not need adjustment.



NOTES:

1. VOL DIF STPT must be set to 0 while the flow loops are being tuned.
2. The Venturi Air Valve command point, GEX DMPR AO3, indicates Venturi Air Valve position. The Venturi Air Valve may be set up for normally open or normally closed operation.
3. Adjusting P gain to a value greater than 0.1 may cause system instability.

Table Statement and Feedback Loop Interaction

General exhaust Air Velocity Control – A table statement and the general exhaust air velocity feedback control loop work together to control the general exhaust air velocity. (The table statement values are generated automatically during calibration of the general exhaust Venturi Air Valve.) The table statement and the control loop work together as follows:

When general exhaust velocity is lower than the first element in the Venturi table (such as 300 or 350 CFM), the feedback control loop suspends operation and the table statement performs all general exhaust air velocity control. (The application uses GEX AIR VOL/GEXDUCT AREA as the value for general air velocity.)

When general exhaust velocity is greater than the first element in the Venturi table, but GEX AIR VOL is less than $\text{GEX FLO STPT} \times \text{LO LIMIT}$, the table statement and the air velocity feedback loop work together to control the general exhaust air velocity. Once GEX AIR VOL becomes greater than GEX FLO STPT, the air velocity feedback loop suspends operation and the table statement takes over all general exhaust air velocity control.

When GEX AIR VOL is greater than $\text{GEX FLO STPT} \times \text{HI LIMIT}$, the table statement and the air velocity feedback loop work to control the general exhaust air velocity. Once GEX AIR VOL becomes less than GEX FLO STPT, the air velocity feedback loop suspends operation and the table statement takes over all general exhaust air velocity control.



NOTE:

If HI and LO LIMIT are set equal, then the feedback loop will always be active as long as the general exhaust air flow is greater than first element in the Venturi table (such as 350 CFM).

The interaction between the table statement and the general exhaust air velocity feedback loop can be summarized as follows:

- When the general exhaust air volume is near setpoint, the table statement controls it.
- When the general exhaust air volume is not near its setpoint (either too high or too low) both the table statement and the general exhaust air velocity feedback loop work together to bring the general exhaust air velocity close to its setpoint as quickly as possible.
- When the general exhaust air velocity is so low that it cannot be accurately read by the general exhaust AVS, the table statement controls it.

Venturi Air Valve Calibration (Mode 1, 3)

The calibration table for Venturi Air Valve(s) determines the relationship between airflow and the voltage curve of the actuator. The calibration table initially contains all zeros by default, that is, it contains no calibration information. This section describes how the user initiates a calibration sequence that populates the calibration table with values of flow at given control voltages.



NOTE:

This automatic calibration sequence relies on values from an associated flow sensor. If running open loop (without a flow sensor), see the *Open Loop Mode* section.

Prerequisites for calibrating Venturi Air Valves:

- Fully operational supply and general exhaust airflow systems.
- Supply and general exhaust Air Velocity Sensors are calibrated and working normally (SUP AIR VOL and GEX AIR VOL cannot be Failed).

The general exhaust Venturi Air Valve is calibrated by setting CAL GEX VLV to YES. Calibration proceeds automatically and takes about 3 minutes, after which CAL (or CAL GEX VLV returns to NO. If calibration is successful, GEX VLV STAT is set to CAL OK. A failed calibration requires checking the equipment for possible causes—loose or kinked flow sensor tubes, improper actuator or valve operation, etc.—followed by recalibration.



NOTE:

The factory default values of GEX VLV STAT is NOTCAL. NOTCAL means that neither the calibration sequence nor manual entry has been done. The value of GEX VLV STAT is set whenever a calibration or table transfer is performed as the last step of the calibration/table transfer. ("Table transfer" is explained at the end of Table 6). GEX VLV STAT is never used for active control decisions. In the case of "PID only" control, the application may remain at NOTCAL indefinitely.

When calibration is complete, the EEPROM automatically stores a table statement of voltages (no loss of values upon power failure) that will be output to the AO point, SUP DMPR AO2 or GEX DMPR AO3, to drive the actuator. Table values are the result of the application's analysis of the voltages that drove the actuator during calibration and the resulting airflow values in cfm. To hedge against airflow accuracy slippage, the supply (or general exhaust) air velocity feedback loop is used along with the table statement to maintain correct airflow out of the Venturi.

Table Access Feature (Mode 1, 3)

In Application 6724 , an embedded table statement and a feedback loop work together to operate the supply or general exhaust Venturi Air Valve.

The table contains 16 pairs of “active” voltage/flow values, and 16 pairs of “inactive” voltage/flow values.

The active values are used to operate the Venturi Air Valve at desired airflows. For example, when the controller is given a flow setpoint value of 500 cfm, it goes to the active portion of the table statement and looks up what the voltage output to the actuator should be in order to achieve 500 cfm. The inactive values are used to edit the active values as explained later in this section.

The *Venturi Table Statement Example* table shows an example of active values in a Venturi table statement after the Venturi Air Valves have been calibrated (note reverse acting exhaust voltage). Table statement values will vary per system.

Venturi Table Statement Example (active values).	
General exhaust Venturi Air Valve	
cfm	volts
0 a)	10 a)
180	5.48
216	5.08
244	4.68
340	3.88
368	3.48
452	2.98
476	2.73
504	2.48
572	1.98
604	1.73
618	1.48
712	0.98
760	0.73
800	0.48
904	0

- a) These voltage/flow values constitute the “low flow” element (or “point”) for the Supply and the General Exhaust Venturi Air Valves. They are shown here with factory default values. They are not altered during calibration—they must be set manually. However, they only need to be set if the Venturi Air Valve is going to be operating at low flow settings of less than 350 fpm. Otherwise, they can be left at default and ignored.

**NOTE:**

The first pair (or “point”) of flow/voltage values in the table statement is the low flow point. It is provided for low flow situations where airflow through the Venturi Air Valve must be controlled at velocities less than 350 fpm. Otherwise, this point can be left at factory default of 0 cfm and 0V (10V if exhaust) and ignored, as is the case in the example table statement in the Table *Venturi Table Statement Example*. See the Table *Venturi Air Valve Table Statement* for how to manually set this point.

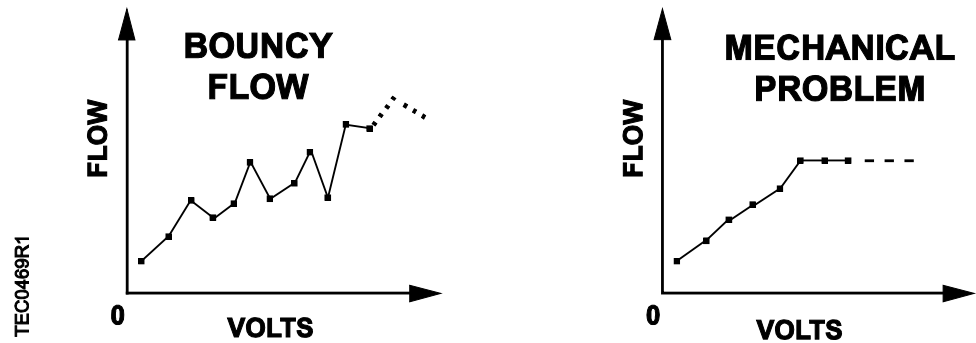
If there is a low flow cfm value, it is taken either from the room schedule or the Venturi Air Valve housing. Cubic feet per minute (cfm) flows in this range (where velocity equals less than 350 fpm) and related voltages must be determined and/or confirmed with help from a balancer. See the Table *Venturi Airflow @ 350 fpm* for cfm flows equal to 350 fpm. The following equation associates airflow to air velocity:

Airflow (cfm) = Velocity (fpm) × Duct Area (sq ft) × Flow Coefficient.

Venturi Airflow @ 350 fpm.	
Valve Size in Inches	cfm
5	48
6	69
8	122
10	191
12	275
Dual 10	380
Dual 12	550
Triple 12	825

During calibration, voltage/flow values are automatically generated. Typically there will be 8 or 9 pairs. The first pair of voltage/flow values—the low flow point—is not generated; it must be set manually. The Venturi Valve actuator is then fed the voltages and the application reads the resulting airflows. At the end of calibration, the airflow readings are analyzed and the calibration is either given a PASS or a FAIL (GEX VLV STAT is set to CAL OK or NOTCAL). To obtain a CAL OK, the airflow readings must increment correctly (the points in the table increase as the voltage increases). For example, if one point on the voltage/flow curve shows 5V and 500 cfm and the next point shows 6V and 450 cfm, the second point (6V, 450 cfm) would fail. But 6V at 550 cfm would pass. (This example assumes the actuator is direct acting, where more volts equal more flow. Exhaust devices are usually reverse acting and have an inverse voltage/flow relationship.) Too many failed airflow points along the voltage/flow curve will result in a NOTCAL status for the calibration.

This application has a table statement edit feature that allows you to view and edit the voltage/flow values in the table. This is useful for fine tuning the air valve to meet precise room flow setpoints and for diagnosing/editing problematic voltage/flow curves (see the *Venturi Air Valve Table Statement* Table).



Problematic Venturi Air Valve Voltage/Flow Curves.



NOTE:

Bouncy flow can mean that airflow through the air valve's flow orifice is too turbulent to be read consistently.

Editing the Venturi Table (Mode 1, 3)

A Venturi Air Valve table statement consists of two sets of voltage/flow values—one set is active and the other inactive. When you run the calibration, the first thing that happens is that the inactive table values are filled in with new values generated by the calibration. Then the application checks these new values to make sure they are good. If they pass (that is, if enough increment correctly), these new values become the active values, and the old active values become inactive. However, if the new values don't pass, then the old active values remain active.

Running a successful calibration sequence is one way of changing/updating the active values. You can also edit the table manually. Normally this is not necessary, but if you are having flow control problems you may need to edit the table.

In order to manually edit the table statement, you must first know which points in the active table need adjusting. This is done by setting V TABLE PT to the appropriate active point values found in *Venturi Air Valve Table Statement Table* in order to gather and view the active voltage/flow curve for the Venturi Air Valve and its actuator. By gathering and analyzing the active voltage/flow values (for example, you can plot them on a graph as in the figure *Problematic Venturi Air Valve Voltage/Flow Curves*), you can decide which one(s) need adjusting. The flow curve should be smooth and incremental.

You can change the active values using the following steps:

1. Set V TABLE PT to a "swap" value that tells the application to exchange active table values with inactive table values (see *Venturi Air Valve Table Statement Table* for swap value).
 - ⇒ This is necessary because the application does not allow active values to be manually overridden.



NOTE:

There is an exception to the rule that active values cannot be manually overridden. The first element in the active portion of the table—the low flow point—can be edited directly. The *Venturi Air Valve Table Statement Table* explains this in more detail.

2. Edit the inactive table values.

⇒ Since you have just switched the active and inactive portions of the table in Step 1, the inactive values are now identical to what the active values were moments ago. You can now edit these new inactive values by using **V TABLE PT** to reference them in **TABLE FLOW** and **TABLE VOLTS**. The *Venturi Air Valve Table Statement Table* explains this in more detail.

3. Set **V TABLE PT** once again to the swap value that places the newly edited inactive values back into the active portion of the table statement (again, the active and inactive portions of the table are simply swapped). However, before the swap is finalized, the application analyzes your proposed values using the same logic as in a regular calibration sequence.

⇒ If your proposed values are good, then the swap is made and the edited values are accepted into the active portion of the table. **GEX VLV STAT** is set to **CAL OK** for exhaust calibration and **SUP VLV STAT** is set to **CAL OK** for supply calibration and control of the Venturi Air Valve resumes.

⇒ If instead either point is set to **NOTCAL**, you need to gather and view the voltage/flow values to see where the problem lies.

The following table lists all values for **V TABLE PT** and describes their use. Any range of points not specifically mentioned (such as 47-60) is unused.

Venturi Air Valve Table Statement		
	V TABLE PT	Description
	0	Default value for V TABLE PT . When V TABLE PT equals 0, changes to TABLE FLOW or TABLE VOLTS are ignored. Setting V TABLE PT to 0 cancels an edit session.
Active Exhaust	31	Setting V TABLE PT to 31 takes the flow (cfm) and voltage values from the first element of the active exhaust table and displays them in TABLE FLOW and TABLE VOLTS where they can be edited. (This is the only active exhaust element (or "point") that can be directly edited.) Flow and voltage values are not allowed to exceed those in active exhaust point number 32. To operate in the range below minimum readable flow (less than 350 fpm), a low flow value in cfm from either the room schedule or the general-exhaust Venturi air valve housing is entered into TABLE FLOW , with the correct corresponding actuator voltage determined/confirmed by the balancer and entered into TABLE VOLTS . NOTE: This point is only necessary for general-exhaust Venturi air valve operation in the range below minimum readable flow (below 350 fpm). Otherwise it can be ignored. This low flow point must be entered only after other non zero points exist in the table as a result of manual edits, or as the result of a prior Venturi auto calibration sequence.
	32 - 46	This portion of the table (32 through 46) can be viewed but not edited directly. When a point is selected (that is, when V TABLE PT is set to a value 32 through 46), the corresponding flow and voltage values are displayed in TABLE FLOW and TABLE VOLTS . Setting V TABLE PT to 32 will result in the smallest readable flow and associated voltage for the exhaust Venturi air valve to be displayed in TABLE FLOW and TABLE VOLTS ; setting V TABLE PT to 46 will result in the maximum flow and associated voltage for the exhaust Venturi air valve to be displayed in TABLE FLOW and TABLE VOLTS . The in between values (33–45) are for the range of flow between min and max. NOTE: The table swap will fail if valid flow and voltage values are not entered in point 46.

Venturi Air Valve Table Statement		
	V TABLE PT	Description
		Table entries marked as failed display FAIL for both flow and voltage.
Inactive Exhaust	91 – 106	This portion of the table can be viewed and edited. The user enters a point (any value 91 through 106) into V TABLE PT and the corresponding cfm and voltage values display in TABLE FLOW and TABLE VOLTS where they can be edited.
Exhaust Swap	121	Setting V TABLE PT to 121 instructs the controller to evaluate the values in the inactive exhaust portion of the table using standard calibration pass/fail logic. If they pass, they are exchanged with those in the active exhaust portion of the table.

**NOTE:**

The factory default value for GEX VLV STAT is NOTCAL which indicates a failure of the calibration or that calibration has not yet been done. The value is set whenever a calibration or table transfer is performed as the last step of the calibration/table transfer. GEX VLV STAT is never used for active control decisions.

**NOTE:**

The calibration table initially contains all zeros by default, that is, it contains no calibration information. When the application detects all zeros, the application does operate, but runs with only PID control. If PID only control is satisfactory for a given job, there is no need to populate the table. Should it be necessary, a populated table can later be edited back to all zeroes to force PID only control.

PID Only (Mode 2)

**NOTE:**

The default P gain value is intended for PID operation in conjunction with the Venturi table. The P gain and Venturi table work together to provide an appropriate response to setpoint changes. When operating without the Venturi table in PID Only mode, the application is slower to respond. Therefore, you should adjust the P gain as needed when operating in PID Only mode to ensure acceptable performance.

The Venturi calibration table initially contains all zeros by default, that is, it contains no calibration information. When the application detects a zero flow for the sixteenth entry (the table entry with the highest flow), the application does operate, but runs with only PID control. If PID only control is satisfactory for a given job, there is no need to populate the Venturi tables.

Open Loop (Mode 3)

This application can operate in open loop mode. In open loop control, there is no airflow sensor to provide an actual air flow measurement. Instead, operation is based completely on the values in the Venturi table. For example, if the actuator's setpoint is 600 cfm, the application will use the Venturi table to derive the voltage setting that generates a flow of 600 cfm and then set the actuator to that voltage to generate the desired flow. Assuming the table has accurate entries, the flow (if it were to be measured) would be at setpoint.

Internally within the application, with open loop control, the flow is always assumed to be at setpoint. As a result there is virtually no difference between flow tracking and setpoint tracking when the actuator being tracked is operating open loop.

Set **GEX AVS ENA** to **NO** to indicate that the general exhaust actuator is to operate open loop. Setting this enable point to **NO** will suppress the AVS failure indication that otherwise would occur when no airflow sensor is connected.

When operating open loop, there is no flow sensor for use in the calibration sequence. Instead, the Venturi table values are directly input by the user. If the Venturi Valve has end points for calibration such as 1200 cfm at end voltage, and an implied lower range of 0 cfm at its other end of the voltage range, the user should enter this information into Point 16, as shown in Example 1 and 2 below. The direction of actuation, Normally Open or Normally Closed is determined by VENTRUI ACT.

Point	Flow	Volt
1	0	0.0
2	0	0.0

15	0	0.0
16	1200	10.0

Example 1 - Table with CFM End Limit – direct acting

It may not be necessary to enter 0 values since 0 values are initially in the table by default when direct acting is selected.

Point	Flow	Volt
1	0	10.0
2	0	10.0

15	0	10.0
16	1200	0.0

Example 2 - Table with CFM End Limits – reverse acting

It may not be necessary to enter 10.0 values since 10.0 values are initially in the table by default when reverse acting is selected.

If specific information about the voltage at low flow is known, that would be entered into point 1 which is reserved for information about low flow. See Examples 3 and 4 below.

Point	Flow	Volt
1	300	3.0
2	0	0.0

15	0	0.0
16	1200	10.0

Example 3 - Table with Voltage End Limits and Low Flow Value – direct acting

Point	Flow	Volt
1	300	7.0
2	0	10.0
3	0	10.0

15	0	10.0
16	1200	0.0

Example 4 - Table with Voltage End Limits and Low Flow Value – reverse acting

You have the option of manually populating the table with additional values as shown in example 5 below. In this case, the table becomes indistinguishable from a table generated via the calibration process.



Point	Flow	Volt
1	300	3.0
2	0	0

7	0	0
8	340	3.2
9	390	3.5
10	521	3.8
11	531	4.1
12	598	4.9
13	691	5.8
14	798	7.0
15	0	0
16	1200	10

Operating Without a Supply or Exhaust

It is possible to run this application without the supply or exhaust if the corresponding flow coefficient is set to zero. When the flow coefficient is zero and the offboard air module is not connected the air velocity sensor will not display a FAIL status and the flow loop will be allowed to run with a flow value of zero. See the *Application Notes* section for more information.

Heating Safety

	⚠ CAUTION
	Do not set UOC SUP MIN or OCC SUP MIN to 0 CFM (0 LPS). Safeties provided by others should require a minimum airflow moving across the heating coils when the modulating heating device is open.
	⚠ CAUTION
	Do not set HTG FLOW MIN to 0 CFM (0 LPS). Safeties provided by others should require a minimum airflow moving across the heating coils when the modulating heating device is open.



NOTE:

As a safety feature, these applications include MODHTG FLO to ensure that adequate airflow is present before heating coils are energized. When the supply airflow (in fpm as derived from the supply air velocity sensor) is greater than MODHTG FLO then the internal point "ok_to_mod" is set to Yes and the modulating heating device is allowed to modulate.

The default value is 300, which means that the airflow over the heating coil must be at least 300 fpm.

Since $CFM = FPM \times Duct\ Area \times Flow\ Coefficient$, the default value of 300 fpm equates to the following cfm:

In a 12-inch diameter duct and a typical flow coefficient of .7, 300 fpm equates to 158 cfm.

$$12\text{ inch diameter} = .75\text{ sq ft} \quad .75\text{ sq ft} * 300\text{ fpm} * .7 = 158\text{ cfm}$$

In an 8-inch diameter duct and a typical flow coefficient of .7, 300 fpm equates to 74 cfm.

$$8\text{ inch diameter} = .35\text{ sq ft} \quad .35\text{ sq ft} * 300\text{ fpm} * .7 = 74\text{ cfm}$$

If the application uses hot water heat rather than electric heat, then MODHTG FLO may be set lower than the default value of 300. This would allow reheating to occur even if the box is operating below its designated minimum flow setting.

Using fpm flow rather than cfm makes the feature less dependent on duct size.

There is hysteresis (deadband) around the flow threshold. The heating turns off below a flow of MODHTG FLO, and does not turn back on until the measured flow rises to a level 50 fpm more than MODHTG FLO. Between MODHTG FLO and MODHTG FLO + 50, the internal point "ok_to_mod" will not change value.

Room Temperature and Setpoint

The application uses the CTL STPT as the setpoint for the Room Temperature PID Loop. When CTL STPT is not overridden and not being controlled by a field panel, then ROOM STPT and CTL STPT are related to each other as follows:

- If ROOM STPT is greater than RM STPT MAX, then CTL STPT is set equal to RM STPT MAX.
- If ROOM STPT is less than RM STPT MIN, then CTL STPT is set equal to RM STPT MIN.
- If ROOM STPT is less than or equal to RM STPT MAX and greater than or equal to RM STPT MIN, then CTL STPT is set equal to ROOM STPT.

If CTL STPT is overridden or being controlled by a field panel, then RM STPT MIN and/or RM STPT MAX have no effect on CTL STPT.

The application also uses CTL TEMP as the temperature input for the Room Temperature PID Loop. When CTL TEMP is not overridden, then:

$$\text{CTL TEMP} = \text{ROOM TEMP} + \text{TEMP OFFSET}.$$

Room Temperature Offset



NOTE:

The Room Temperature Offset feature is optional.

TEMP OFFSET is a user-adjustable offset that will compensate for deviations between the value of ROOM TEMP and the actual room temperature. This corrected value is displayed in CTL TEMP.

$$\text{CTL TEMP} = \text{ROOM TEMP} + \text{TEMP OFFSET}$$

Example

If the actual room temperature is 72.0°F, and the value of ROOM TEMP is 73.0°F, then the value entered into TEMP OFFSET is **-1.0**. In this case, the value of ROOM TEMP would read 73.0°F, but the value of CTL TEMP would read 72.0°F.

Room Unit Operation

Stat Supervision

STAT SUPV is a configurable, enumerated point (values are additive). This point tells the controller what kind of room unit is connected and how to respond to a loss of communication between a Series 2200 and 3200 type Room Units, thermistor inputs, and the controller.

The default value for STAT SUPV using Series 2200 or 3200 units must be set to a value greater than 0 (zero), to define temperature sensing and thermistor inputs. See the *Start-up Procedures* for more information.

A value of 1 means that if communication is lost for at least one minute, CTL TEMP will have a status of Failed. A value of 3 means that both CTL TEMP and RM RH will be Failed and a value of 7 means CTL TEMP, RM RH and RM CO₂ will be Failed.

Value	Description
1	Temperature sensing only
2	Relative Humidity (RH) sensing
4	CO ₂ sensing
8	To select a 100K Ω Thermistor on AI 5 (for long board), AI 3 (for short board)
16	To select a 100K Ω Thermistor on AI 4

See *Sensors and Transducers Configuration and Sizing* for part numbers and ordering information.

CO₂ Monitoring

RM CO₂ displays the CO₂ value in units of parts-per-million (PPM). RM CO₂ can be unbundled for monitoring purposes.

Room RH

RM RH displays the relative humidity value in percent. RM RH can be unbundled for monitoring purposes.

PPCL STATUS

PPCL STATUS displays LOADED or EMPTY.

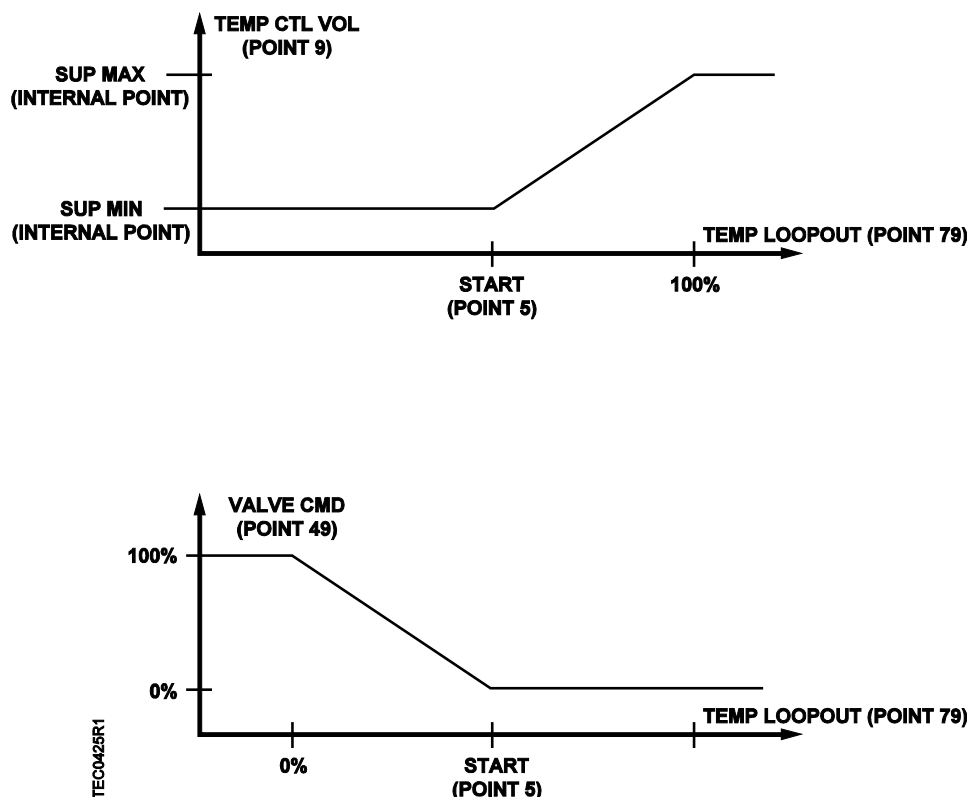
LOADED = PPCL programming is present in the controller. A new application number must be assigned (12000 through 12999).

EMPTY = NO PPCL programming is present.

Temperature Control Loop

Whenever the controller is in VAV control mode, the temperature control portion of Application 6724 works as follows:

The controller adjusts the supply airflow and the reheat valve as necessary to maintain CTL TEMP at CTL STPT. (When neither CTL TEMP nor CTL STPT is overridden, this means the controller tries to maintain ROOM TEMP at ROOM STPT.) The temperature control loop calculates the value of TEMP LOOPOUT. This value is used to sequence the cooling flow and the heating valve. See the following figure. The loop is tuned by adjusting the values of the feedback gains (ROOM P GAIN and ROOM I GAIN and the sample interval, LOOP TIME.



Temperature Control Sequence.

The range of TEMP LOOPOUT is 0 to 100%. Higher values indicate a need for more cooling (or less heat). The Figure *Temperature Control Sequence* shows that as the value of TEMP LOOPOUT moves from START to 0%, and the reheat VALVE CMD is modulated from 0 to 100%. VALVE CMD is converted to a voltage and put out on REHEAT A01. The setup points, VALVE CLOSED and VALVE OPEN, tell the controller the voltage range the valve needs to reach at each end of its stroke.

The controller modulates the cooling flow in sequence with the valve. In this application, temperature control is not the only factor affecting the supply airflow—room pressurization has a higher priority. Therefore, the temperature control sequence does not calculate the supply flow setpoint. Instead, it calculates the amount of supply airflow needed for cooling (TEMP CTL VOL). If this value is compatible with correct room pressurization, it is used as the supply flow setpoint. If not, the actual setpoint, SUP FLO STPT, may be higher or lower than TEMP CTL VOL. As the value of TEMP LOOPOUT moves from START to 100%, TEMP CTL VOL is modulated from the supply minimum to the supply maximum. (During the occupied period, the supply minimum is OCC SUP MIN and the supply maximum is OCC SUP MAX. During the unoccupied period, the supply minimum is UOC SUP MIN and the supply maximum is UOC SUP MAX.

The temperature sequencing point, START, determines what part of the operating range is used for cooling and reheat. By default, it is set to allow 50% of the range to cooling and 50% to reheat. You can alter that balance so it matches the heating and cooling capacities of the equipment. For instance, if the reheat valve has three times the effect of the cooling flow, then setting START to 75% gives an approximately uniform thermal affect across the range of TEMP LOOPOUT. In some cases, this makes it easier to tune the PID loop.

When the controller is operating in the constant volume mode, TEMP LOOPOUT is not allowed to get numerically bigger than the value of START. This means that the application will control the temperature only by modulating the reheat valve; it will make no attempt to control temperature by varying the airflow in the space. During constant volume control, TEMP CTL VOL will remain equal to zero.

Alarms

The controller is equipped with ventilation and pressurization alarms. It does not contain temperature alarms. The controller's alarms are designed to:

- Inform room occupants of hazards.
- Inform building operation personnel that the system is not functioning correctly.
- Supply data for documenting laboratory safety records through trending.

These alarms can be annunciated locally and/or broadcast across a network.

Ventilation Alarm

The alarm level depends on whether the room is occupied or vacant. When the OCC.UNOCC point indicates occupancy, the OC V ALM LVL is used. When the OCC.UNOCC point indicates vacancy, the UC V ALM LVL is used.



NOTE:

In the following discussion, the currently active supply flow minimum is OCC SUP MIN during occupancy and UOC SUP MIN during the unoccupied period. Likewise, the currently active general exhaust box minimum is OCC GEX MIN during occupancy and UOC GEX MIN during the unoccupied period.

The ventilation alarm, VENT ALM, indicates that there is something wrong with the ventilation to the room. VENT ALM has an adjustable alarm level that can vary with the occupancy status of the room. An adjustable delay timer, VENT ALM DEL, prevents nuisance alarms.

VENT ALM is turned on when at least one of the following conditions is true:

- The supply flow to the room, TOTL SUPPLY, stays below the alarm level, for a time at least equal to VENT ALM DEL.
- SUP AIR VOL stays below the currently active supply minimum, for a time at least equal to VENT ALM DEL.
- GEX AIR VOL stays below the currently active general exhaust box minimum, for a time at least equal to VENT ALM DEL.

It is turned off only when all of the following conditions are true:

- The TOTL SUPPLY stays above the alarm level, for a time at least equal to the alarm delay.
- SUP AIR VOL stays above the currently active supply minimum, for a time at least equal to VENT ALM DEL.
- GEX AIR VOL stays above the currently active general exhaust box minimum, for a time at least equal to VENT ALM DEL.

If the current conditions will neither turn on the ventilation alarm nor shut off the alarm, then VENT ALM will keep its current value.

Setting the alarm level to zero means the ventilation alarm will not turn on just because of a low value for TOTL SUPPLY.



Even if the alarm level is set to zero, the ventilation alarm will still turn on if:

- SUP AIR VOL stays below the currently active supply minimum, for a time at least equal to VENT ALM DEL.

and/or

- GEX AIR VOL stays below the currently active general exhaust box minimum, for a time at least equal to VENT ALM DEL.

Pressurization Alarm

The pressurization alarm, VOL DIF ALM indicates that the difference between supply and exhaust flow is not what it should be, or that the controller can't calculate the flow difference, VOL DIFFRNC, because it has lost a flow signal. The *Failure Mode Sequence* figure lists reasons why VOL DIFFRNC may fail.

The pressurization alarm point is turned on when at least one of the following conditions occurs:

- VOL DIFFRNC has a status of Failed.
- VOL DIFFRNC stays below VOL DIF STPT – DIF ALM DBD for a time at least equal to DIF ALM DEL.
- VOL DIFFRNC stays above VOL DIF STPT + DIF ALM DBD for a time at least equal to DIF ALM DEL.



WARNING

To ensure that VOL DIF ALM turns on before the pressure in the room changes sign, DIF ALM DBD must be less than the absolute value of VOL DIF STPT.

For example, if negative pressure is desired and VOL DIF STPT equals 70 cfm and DIF ALM DBD is 200 cfm, then the room could go positive by almost 130 cfm without the pressure alarm turning on. In this case, if you want the alarm to turn on before the room changes sign, then you must set DIF ALM DBD to be less than 70 cfm.

The pressurization alarm point is turned off when all of the following conditions occur:

- VOL DIFFRNC has a status of Normal.
- VOL DIFFRNC stays above VOL DIF STPT – DIF ALM DBD for a time at least equal to DIF ALM DEL.
- VOL DIFFRNC stays below VOL DIF STPT + DIF ALM DBD, for a time at least equal to DIF ALM DEL.

DIF ALM DBD and DIF ALM DEL can be configured to prevent nuisance alarms.

Local Annunciation

ALARM ENA is an analog point whose value determines whether or not a particular alarm activates ALARM DO7.

For ALARM ENA, the terms enabled and not enabled do not mean that a particular alarm is enabled or not. It means whether or not a particular alarm will or will not activate ALARM DO7. For example, if ALARM ENA is set to 1 (Vent Alarm Enabled) and a ventilation alarm occurs, then both VENT ALM and ALARM DO7 will turn on. However, if ALARM ENA is not Vent Alarm Enabled and a ventilation alarm occurs, VENT ALM will turn on, but ALARM DO7 will not.

ALARM ENA Values.	
	ALARM ENA
0 default	No alarms are enabled.
1	Vent Alarm is enabled.
2	Alarm Switch is enabled.
3	Vent Alarm and Alarm Switch are enabled
4	Dif Alarm is enabled.
5	Vent Alarm and Dif Alarm are enabled
6	Alarm Switch and Dif Alarm are enabled
7	Vent Alarm, Alarm Switch, and Dif Alarm are all enabled



NOTE:

If ALARM ENA is set greater than 7, it will default to 0.

ALM ENA is additive. For example, if ALM ENA equals 5, then either a ventilation or a pressurization alarm would activate ALARM DO7, but the alarm switch would not.

ALARM DO7 is used to operate a local alarm annunciation device such as a light or horn in or near the room. Inputs can be set up to annunciate alarms from any combination of the following sources:

- Pressurization alarm point, VOL DIF ALM
(To connect VOL DIF ALM to DO 7, set ALM ENA to a value that enables the pressure alarm (4, 5, 6 or 7).)
- Ventilation alarm point, VENT ALM
(To connect VENT ALM to DO 7, set ALM ENA to a value that enables the ventilation alarm (1, 3, 5 or 7).)
- DI connected to a switch in the room, ALM SWIT DI6
(To connect ALM SWIT DI6 to DO 7, set ALM ENA to a value that enables the Alarm Switch (2, 3, 6 or 7).)
- Network alarm point, NET ALM CMD
(NET ALM CMD is always enabled for local annunciation.)

ALARM DO7 turns ON if any of the enabled alarm sources indicate an alarm. ALARM DO7 cannot be overridden.

NET ALM CMD can be commanded with Insight software or PPCL to send an alarm state from the field panel. This makes it possible to program unique alarm criteria and annunciate alarms in specific rooms.

Network Annunciation

If the LCM is connected to a field panel, alarms can be reported using the Insight® software, or by using a printer that is set up in a building manager's office to receive alarms. Points in the controller must be entered in the field panel's point database (referred to as unbundling) and defined as alarmable. If, for example, the room pressurization alarm (VOL DIF ALM) is unbundled in a field panel and a pressurization alarm is triggered, an alarm will be annunciated across the network.

Alarms in Open Loop Mode

When operating a Venturi valve in open loop mode, there is no sensor to measure actual flow. Instead, flow estimates are based on the current commanded valve position.

Actuator Position on Return from Power Failure

Supply Damper

On a return from power failure, the damper-command DOs (DOs1 through 2) remain OFF for 5 seconds prior to resuming control. Because of this it is recommended that the Supply Damper Motor Setup be set to Enabled (normally closed) for rooms where negative or neutral pressurization is required and Enabled and Reversed (normally open, where the actuator is retracted) for positively pressurized rooms.

Additive Values that Determine the Value of MTR SETUP			
	Not Used	Enabled	Enabled and Reversed
Motor 1 (supply damper – DO 1 and DO 2)	0	1	3

GEX Valve

On a return from power failure, the AOs remain OFF for 5 seconds prior to resuming control. Because of this it is recommended that the General Exhaust Valve be set to Normally Opened for rooms where negative or neutral pressurization is required and Normally Closed for positively pressurized rooms. Setting of the Venturi direction is via VENTURI ACT.

	VENTURI ACT
0	Exhaust Venturi Valve is Normally Closed (Direct Acting)
1 (default)	Exhaust Venturi Valve is Normally Opened (Reverse Acting)

Floating Control Actuation Auto-correct

In addition to the existing options for floating control actuator full stroke actions; all floating control actuators are provided with additional logic to fully drive open or closed when commanded to 100% or 0%.

Operation of AVS FAILMODE

AVS FAILMODE is an enumerated point that describes how the Supply Damper and the General Exhaust Venturi Air Valve will respond if one or both Air Velocity Sensors (AVS) fail. It can handle positively pressurized rooms as well as negatively pressurized rooms.

The default value of AVS FAILMODE is **0**. This default causes both the Supply and General Exhaust Dampers to hold their current position when an AVS fails. Open Supply, Open Exhaust and Close Supply, Close Exhaust are not defined AVS FAILMODE states.

AVS failure and AVS FAILMODE values.	
	AVS FAILMODE
0 (default)	Hold Supply, Hold General Exhaust
1	Hold Supply, Open General Exhaust
2	Hold Supply, Close General Exhaust
3	Open Supply, Hold General Exhaust
4	Close Supply, Hold General Exhaust
5	Close Supply, Open General Exhaust
6	Open Supply, Close General Exhaust
7	VENTILATION
8	PRESSURE

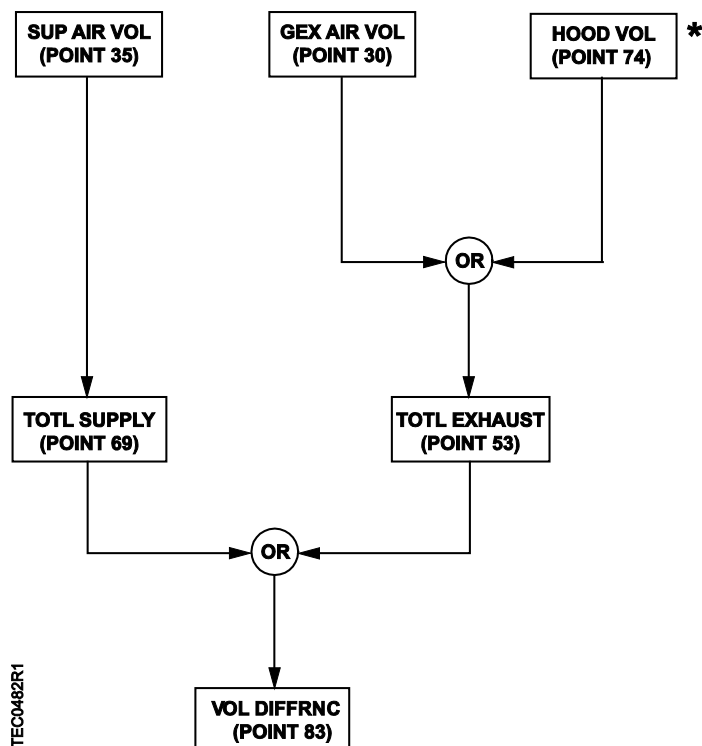
If AVS FAILMODE equals **7**, the supply actuator will hold. The general exhaust actuator will also hold if a fume hood is present (that is, if MAX HOOD VOL > 0). If a fume hood is absent, then the general exhaust actuator will close if the room is being positively pressurized and open if the room is neutral or is being negatively pressurized (that is if VOL DIF STPT is equal to or greater than 0).

If AVS FAILMODE equals **8**, the supply actuator will open if the room is being positively pressurized and close if the room is neutral or is being negatively pressurized. The general exhaust actuator will hold if a fume hood is present. If a fume hood is absent, then the general exhaust actuator will close if the room is being positively pressurized and open if the room is neutral or is being negatively pressurized.

If AVS FAILMODE is set greater than 8, it will display a 0 and act as though it was set to 0.

Fail Mode Operation

If one of the controller's accessories (inputs) fails, a failure mode sequence is initiated that leads to the failure of VOL DIFFRNC. The figure shows the order in which points will fail.



* If MAX HOOD VOL is set to 0, a "Failed" status of HOOD VOL will not initiate a failure in TOTL EXHAUST or VOL DIFFRNC. See Fume Hood Flow Input.

Air Velocity Sensors – If one or both of the LCM air sensor signals (SUP AIR VOL, GEX AIR VOL) are out of range (for example, improper wiring to/from the Offboard Air Module(s), tubing not connected or connected backward), then the actions of the supply and general exhaust Venturi Air Valves will depend on the value of AVS FAILMODE. Once GEX AIR VOL and SUP AIR VOL are normal, the supply and general exhaust Venturi Air Valves return to normal operation.

See *Operation of AVS FAILMODE* for more information.

Fume Hood Flow – If MINHOODVOLTS is 1 Volt or higher, HOOD VOL will fail when the LCM receives an invalid (less than .4 Vdc) fume hood flow signal or when the fume hood controller (FHC) loses power or when it loses its flow sensor. If HOOD VOL fails and if VOL DIF STPT is greater than or equal to 0 (negative or neutral pressurization required), the supply and exhaust loops assume a hood exhaust value of 0 cfm and continue to maintain user-defined pressurization. If HOOD VOL fails and VOL DIF STPT is less than 0 (positive pressurization required), the supply and exhaust loops assume the hood's exhaust value is equal to MAX HOOD VOL and continue to maintain user-defined pressurization. When the LCM is being used with fume hoods, and MAX HOOD VOL is set above its default of 0 cfm, a failure of HOOD VOL causes TOTL EXHAUST and VOL DIFFRNC to fail in succession (Figure 5). When VOL DIFFRNC fails, the pressurization alarm point, VOL DIF ALM, turns on automatically. If any of these points have been defined as alarmable and unbundled at the field panel, an alarm will be annunciated across the network.

If MINHOODVOLTS is set to a value of less than 1 (including 0), the fail voltage sensing at .4 Vdc as described above is disabled. However, if there is a break (open circuit) in the wiring, both the AI 3 point and HOOD VOL point will indicate failure.



NOTE:

If desired, the LCM can be used without any fume hoods attached. In this case, MAX HOOD VOL should be set to 0 cfm to disable the alarming that would occur if the fume hood flow input drops below 1 Vdc.

Laboratory Room Controller – If the LCM power fails, all actuators default to their user-defined fail-safe states. Since there is no power to the controller, no LEDs are available.

Room Temperature Sensor – If the room temperature sensor fails while CTL TEMP is not overridden or is not being adjusted by a field panel, then ROOM TEMP and CTL TEMP both display as “Failed” and temperature control is suspended at the current value of TEMP LOOPOUT. If ROOM TEMP is unbundled in a field panel and defined as alarmable, an alarm will be annunciated across the network.

If the room temperature sensor fails while CTL TEMP is overridden or is being adjusted by a field panel, then ROOM TEMP displays as “Failed”. CTL TEMP will continue to be overridden or adjusted by the field panel and room temperature control proceeds as normal. CTL TEMP will continue to have a status of NORMAL. If ROOM TEMP is unbundled in a field panel and defined as alarmable, an alarm will be annunciated across the network.

Room Temperature Setpoint Dial – If the room temperature setpoint dial fails while CTL STPT is not overridden or is not being adjusted by a field panel, then ROOM STPT and CTL STPT both display as “Failed” and the last known good value of ROOM STPT is used to determine the current value of CTL STPT. The rest of the room temperature PID loop is unaffected by the setpoint dial failure. If ROOM STPT is unbundled in a field panel and defined as alarmable, an alarm will be annunciated across the network.

If the room temperature sensor fails while CTL STPT is overridden or is being adjusted by a field panel, then ROOM STPT displays as “Failed”. CTL STPT will continue to be overridden or adjusted by the field panel and room temperature control proceeds as normal. CTL STPT will continue to have a status of NORMAL. If ROOM STPT is unbundled in a field panel and defined as alarmable, an alarm will be annunciated across the network.



NOTE:

When using a Series 2000 Room Thermostat:

During **unoccupied mode**, you cannot change the Room Setpoint using a Siemens Building Technologies Series 2000 thermostat. Any attempt to change Room Setpoints during unoccupied mode using a Series 2000 stat will be ignored.

During **occupied mode**, the Room Setpoint can be changed using a Series 2000 stat, but if it is, then the controller initial values should be uploaded to the field panel.

Otherwise the LCM will not keep the adjusted Room Setpoint value upon return from a power failure.

Application Notes

Operating Without a General Exhaust Box

This application can operate without a general exhaust box. If a general exhaust box is not being controlled, set TRACK METHOD to FLOW and set the following points:

- TRACK MODE to 0.
A value of 0 = STE (supply tracks exhaust) Flow Tracking, which should be used for both the occupied and unoccupied modes.
- GEX FLO COEF to 0.
When GEX FLO COEF equals 0, GEX AIR VOL will always read 0, but will never show as Failed.
- OCC GEX MIN and UOC GEX MIN to 0.
If these two points are not set to 0, GEX AIR VOL—which will read 0 since GEX FLO COEF was set to 0—will be less than the general exhaust box minimum, resulting in a false ventilation alarm.

The application varies the supply airflow as the fume hood flow changes, in order to maintain the proper room pressurization. The supply airflow is not varied for cooling purposes; all temperature control is done by the reheat valve.

Because of this, START should be set to 100 to allow the reheat valve to be controlled by the full range of TEMP LOOPOUT and to prevent the room temperature PID Loop from winding up.

Operating Without a Supply Box

This application can operate without a supply box. If a supply box is not being controlled, set TRACK METHOD to FLOW and set the following points:

- TRACK MODE to 3
(a value of 3 = ETS Flow Tracking, which should be used for both the occupied and unoccupied modes),
- SUP FLO COEF to 0.
When SUP FLO COEF equals 0, SUP AIR VOL will always read 0, but will never show as Failed.
- OCC SUP MIN and UOC SUP MIN to 0.
If these two points are not set to 0, SUP AIR VOL—which will read 0 since SUP FLO COEF was set to 0—will be less than the supply box minimum, resulting in a false ventilation alarm.

This setup is useful when the room has a constant source of supply air from other equipment or sources not connected to the controller. If you enter this constant supply air volume value into OTHER SUP, the application will vary the general exhaust airflow as the fume hood flow changes, in order to maintain the proper room pressurization.

Since all temperature control will be done by the reheat valve, START should be set to 100 to allow the reheat valve to be controlled by the full range of TEMP LOOPOUT and to prevent the room temperature PID Loop from winding up.

Wiring Diagrams



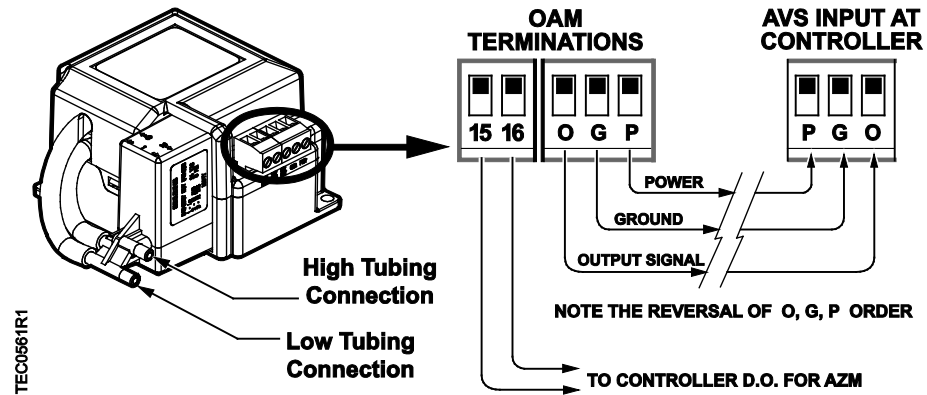
⚠ CAUTION

Controllers will be damaged/destroyed if offboard air module(s) are not wired correctly and power is applied.



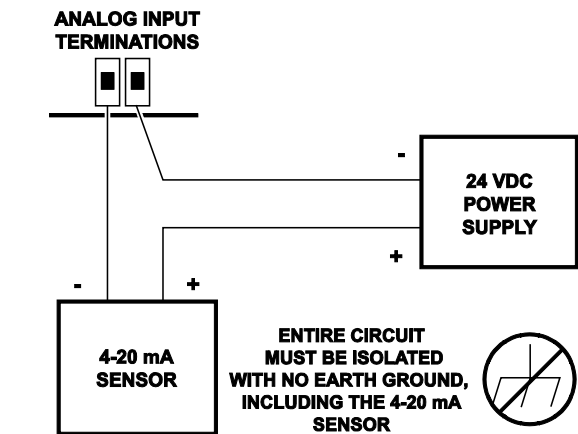
NOTE:

For OAMs prior to 3/09 “O G P” is labeled as “S + -”.



Offboard Air Module Wiring.

	<p>⚠ CAUTION</p> <p>The LCM-OAVS has two terminal blocks with terminations numbered identically (terminations 1 through 16). DO NOT get these mixed up with each other.</p> <p>If the LCM-OAVS is not connected as shown, it is not resistant to electrical surges. It is also susceptible to interference from other equipment.</p>
	<p>⚠ CAUTION</p> <p>A separate power supply is required if a 4-20 mA sensor is used.</p> <p>Failure to follow wiring precautions will result in equipment damage.</p>



⚠ CAUTION:



Each 4-20A sensor requires a **SEPARATE**, dedicated power limited 24 VDC power supply. **DO NOT** use the same transformer to power both the sensor and controller.

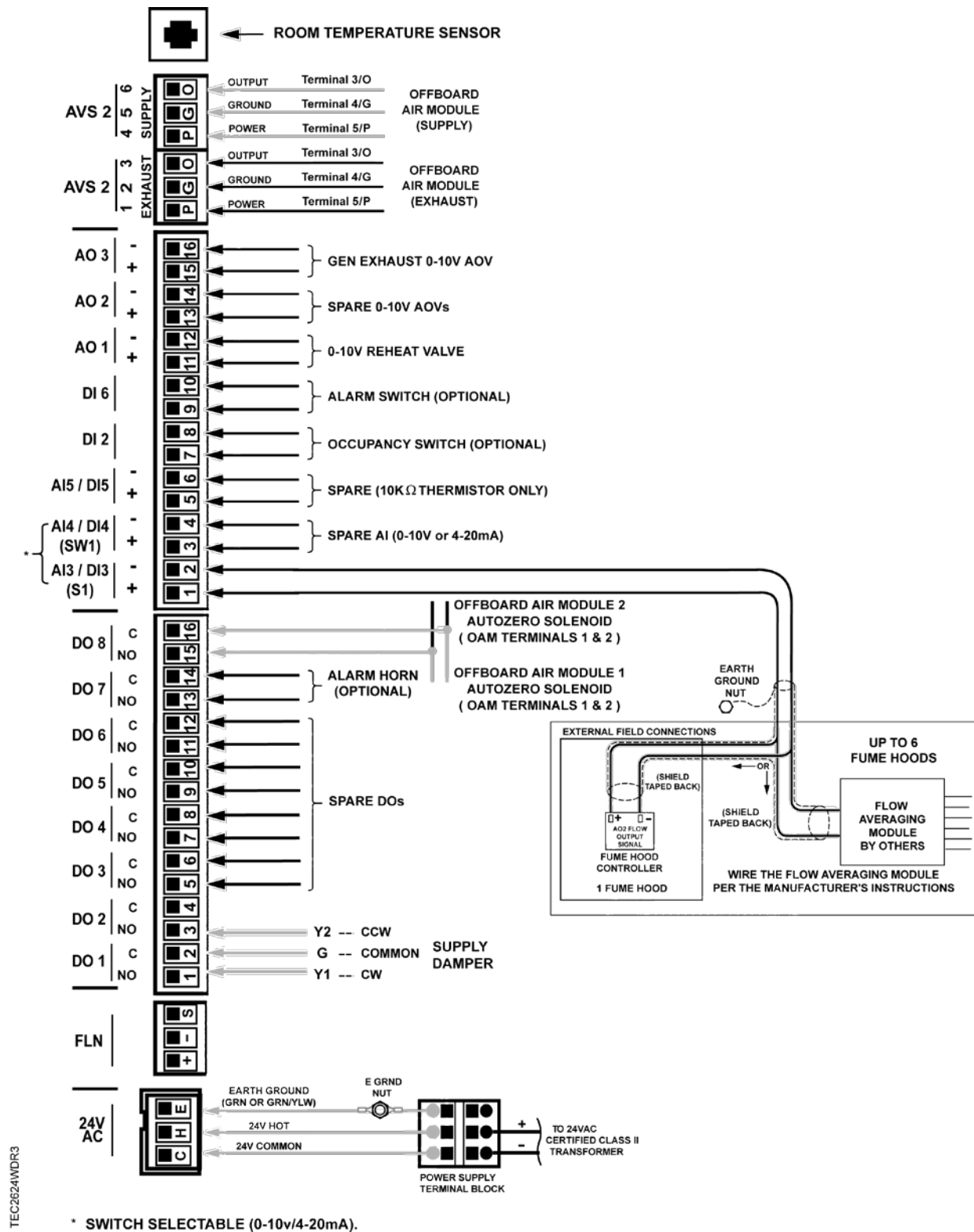
Wiring for AI 3 with a 4 to 20mA Sensor.



NOTE:

If the voltage/current switch is set to current and a 4 to 20mA sensor is connected to AI 3, then special wiring requirements must be followed.

	<p>⚠ CAUTION</p> <p>The controller's DOs control 24 Vac loads only.</p> <p>The maximum rating is 12 VA for each DO. Use an interposing 24 Vac relay module (such as 540-147) for any of the following:</p> <ul style="list-style-type: none"> - VA requirements higher than 12 VA - Separate transformers to power the load - Direct current (DC) power requirements
	<p>⚠ CAUTION</p> <p>The controller has two terminal blocks with terminations numbered identically (termination 1 through 16). DO NOT get these mixed up with each other.</p> <p>If the controller is not connected as shown, it is not resistant to electrical surges. It is also susceptible to interference from other equipment .</p> <p>See the <i>Offboard Air Module Wiring</i> figure to correctly wire the Offboard Air Module(s).</p> <p>See the <i>Wiring of Optional 4-20 mA Sensor</i> figure to wire a 4-20 mA at AI 4 (optional).</p>



BACnet LCM-OAVS Slow Actuation Damper Supply/Venturi Exhaust – Application 6724 Wiring Diagram.

Point Database Application 6724

Object Type	Object Number	Object Name Descriptor	Factory Default (SI Units)	Eng Units (SI Units)	Range	Active Text	Inactive Text
AO	1	CTLR ADDRESS	99	--	0-255	--	--
AO	2	APPLICATION	6797	--	0-32767	--	--
AO	3	TEMP OFFSET	0.0 (0.0)	DEG F (DEG C)	-31.75-32	--	--
AO	{04}	ROOM TEMP	74.0 (23.44888)	DEG F (DEG C)	48-111.75	--	--
AO	5	OCC DIF STPT	400 (188.7599)	CFM (LPS)	-8000-8380	--	--
AO	6	UOC DIF STPT	400 (188.7599)	CFM (LPS)	-8000-8380	--	--
AO	7	RM STPT MIN	55.0 (12.80888)	DEG F (DEG C)	48-111.75	--	--
AO	8	RM STPT MAX	90.0 (32.40888)	DEG F (DEG C)	48-111.75	--	--
AO	{09}	TEMP CTL VOL	0 (0.0)	CFM (LPS)	0-32764	--	--
AO	{10}	TABLE FLOW	0 (0.0)	CFM (LPS)	0-32764	--	--
AO	12	OCC ENA	0	--	0-255	--	--
AO	{13}	ROOM STPT	74.0 (23.44888)	DEG F (DEG C)	48-111.75	--	--
AI	{14}	AI 4	0	PCT	0-102	--	--
AI	{15}	HOOD SIG AI3	0	VOLTS	0-10.2	--	--
AO	16	VENT ALM DEL	30	SEC	0-255	--	--
AO	17	ALARM ENA	0	--	0-255	--	--
AO	18	START	50	PCT	0-102	--	--
BO	{19}	OCC BUTTON	OFF	--	Binary	ON	OFF
BO	{21}	OCC.UNOCC	OCC	--	Binary	UNOCC	OCC
BO	{22}	VOL DIF ALM	OFF	--	Binary	ON	OFF
BO	{23}	NET ALM CMD	OFF	--	Binary	ON	OFF
BI	{24}	OCC SWIT DI2	OFF	--	Binary	ON	OFF
BO	{25}	BUTTON CMD	OCC	--	Binary	UNOCC	OCC
AO	26	GEX P GAIN	0.015	--	0-4.095	--	--
BI	{27}	ALM SWIT DI6	OFF	--	Binary	ON	OFF
AO	28	TRACK MODE	0	--	0-255	--	--
BO	{29}	NET OCC CMD	OCC	--	Binary	UNOCC	OCC
AI	{30}	GEX AIR VOL	0 (0.0)	CFM (LPS)	0-32764	--	--
AO	{31}	OCC SUP MAX	3400 (1604.46)	CFM (LPS)	0-32764	--	--

Object Type	Object Number	Object Name Descriptor	Factory Default (SI Units)	Eng Units (SI Units)	Range	Active Text	Inactive Text
AO	{32}	OCC SUP MIN	340 (160.446)	CFM (LPS)	0-32764	--	--
AO	{33}	OCC GEX MAX	1100 (519.09)	CFM (LPS)	0-32764	--	--
AO	{34}	OCC GEX MIN	600 (283.14)	CFM (LPS)	0-32764	--	--
AI	{35}	SUP AIR VOL	0 (0.0)	CFM (LPS)	0-32764	--	--
AO	36	SUP FLO COEF	0.73	--	0-2.55	--	--
AO	{37}	REHEAT AO1	0	VOLTS	0-10.23	--	--
AO	38	DIF ALM DBD	100 (47.19)	CFM (LPS)	0-4092	--	--
AO	39	DIF ALM DEL	30	SEC	0-255	--	--
AO	40	AVS FAILMODE	0	--	0-255	--	--
BO	{41}	DO 1	OFF	--	Binary	ON	OFF
BO	{42}	DO 2	OFF	--	Binary	ON	OFF
BO	{43}	DO 3	OFF	--	Binary	ON	OFF
BO	{44}	DO 4	OFF	--	Binary	ON	OFF
BO	45	TRACK METHOD	FLOW	--	Binary	FLOW	STPT
BO	{46}	DO 5	OFF	--	Binary	ON	OFF
BO	{47}	ALARM DO7	OFF	--	Binary	ON	OFF
BO	{48}	AUTOZERO DO8	OFF	--	Binary	ON	OFF
AO	{49}	VALVE CMD	0	PCT	0-102	--	--
BO	50	GEX VLV STAT	NOTCAL	--	Binary	NOTCAL	CAL OK
AO	52	MAX HOOD VOL	0 (0.0)	CFM (LPS)	0-32764	--	--
AI	{53}	TOTL EXHAUST	0 (0.0)	CFM (LPS)	0-32764	--	--
AO	54	GEX FLO COEF	0.73	--	0-2.55	--	--
AO	{55}	AO2	0	VOLTS	0-10.23	--	--
AO	{56}	GEX DMPR AO3	0	VOLTS	0-10.23	--	--
AO	57	VALVE CLOSED	10	VOLTS	0-10.23	--	--
AO	58	VALVE OPEN	0	VOLTS	0-10.23	--	--
AO	60	GEXDUCT AREA	1.0 (0.09292)	SQ. FT (SQ M)	0-6.375	--	--
AO	{61}	OTHER SUP	0 (0.0)	CFM (LPS)	0-16380	--	--
AO	{62}	SUP DMP CMD	0	PCT	0-102	--	--
AO	65	ROOM P GAIN	20.0 (36.0)	--	0-8191.75	--	--
AO	66	ROOM I GAIN	0.01 (0.018)	--	0-32.767	--	--
AO	{67}	UOC GEX MAX	1000 (471.9)	CFM (LPS)	0-32764	--	--

Object Type	Object Number	Object Name Descriptor	Factory Default (SI Units)	Eng Units (SI Units)	Range	Active Text	Inactive Text
AO	{68}	UOC GEX MIN	500 (235.95)	CFM (LPS)	0-32764	--	--
AI	{69}	TOTL SUPPLY	0 (0.0)	CFM (LPS)	0-32764	--	--
AO	70	SUP P GAIN	0.015	--	0-4.095	--	--
AO	{71}	UOC SUP MAX	2200 (1038.18)	CFM (LPS)	0-32764	--	--
AO	{72}	UOC SUP MIN	220 (103.818)	CFM (LPS)	0-32764	--	--
AO	{73}	CTL STPT	74.0 (23.44888)	DEG F (DEG C)	48-111.75	--	--
AI	{74}	HOOD VOL	0 (0.0)	CFM (LPS)	0-32764	--	--
AO	76	VOLUME STATE	1	--	0-255	--	--
BO	{77}	DO 6	OFF	--	Binary	ON	OFF
AO	{78}	CTL TEMP	74.0 (23.44888)	DEG F (DEG C)	48-111.75	--	--
AO	{79}	TEMP LOOPOUT	400	PCT	0-818.8	--	--
AI	{83}	VOL DIFFRNC	0 (-0.0001)	CFM (LPS)	-8000-8380	--	--
AI	{84}	AI 5	74.0 (23.496)	DEG F (DEG C)	37.5-165	--	--
AO	{85}	GEX FLO STPT	0 (0.0)	CFM (LPS)	0-16380	--	--
AO	86	FAIL LIMIT	40 (18.876)	CFM (LPS)	0-32764	--	--
BO	{87}	CAL GEX VLV	NO	--	Binary	YES	NO
AO	{88}	VOL DIF STPT	400 (188.7599)	CFM (LPS)	-8000-8380	--	--
AO	{89}	OTHER EXH	0 (0.0)	CFM (LPS)	0-16380	--	--
AO	90	OC V ALM LVL	0 (0.0)	CFM (LPS)	0-32764	--	--
AO	91	UC V ALM LVL	0 (0.0)	CFM (LPS)	0-32764	--	--
BO	{92}	VENT ALM	OFF	--	Binary	ON	OFF
AO	{93}	SUP FLO STPT	0 (0.0)	CFM (LPS)	0-16380	--	--
BO	{94}	CAL AIR	NO	--	Binary	YES	NO
AO	95	CAL SETUP	4	--	0-255	--	--
AO	96	CAL TIMER	12	HRS	0-255	--	--
AO	97	SUPDUCT AREA	1.0 (0.09292)	SQ. FT (SQ M)	0-6.375	--	--
AO	98	LOOP TIME	5	SEC	0-255	--	--
AO	{99}	ERROR STATUS	0	--	0-255	--	--
AO	{104}	STAT SUPV	0	--	0-255	--	--
AO	105	VENTURI ACT	1	--	0-255	--	--
AO	106	MODHTG FLO	300	FPM (MPS)	0-4095	--	--

Object Type	Object Number	Object Name Descriptor	Factory Default (SI Units)	Eng Units (SI Units)	Range	Active Text	Inactive Text
			(1.524)				
AO	107	DO DIR.REV	0	--	0-255	--	--
AO	{108}	RM RH	50	PCT	0-102	--	--
AO	109	FAIL TIME	60	SEC	0-510	--	--
AO	110	MTR SETUP	0	--	0-255	--	--
AO	{111}	SUP DMP POS	0	PCT	0-102	--	--
AO	112	MTR1 TIMING	95	SEC	0-511	--	--
AO	113	MTR1 ROT ANG	90	--	0-255	--	--
AO	117	MINHOODVOLTS	1	VOLTS	0-10.2	--	--
AO	{118}	RM CO2	1000	PPM	0-8191	--	--
AO	{119}	TABLE VOLTS	0	VOLTS	0-10.23	--	--
AO	{120}	V TABLE PT	0	--	0-255	--	--
AO	121	HI LIMIT	1	--	0-2.55	--	--
AO	122	LO LIMIT	1	--	0-2.55	--	--
BO	124	G OPEN LOOP	NO	--	Binary	YES	NO
AO	125	SUP MAX RATE	0 (0.0)	FPM (MPS)	0-4095	--	--
AO	126	GEX MAX RATE	0 (0.0)	FPM (MPS)	0-4095	--	--
BO	{127}	PPCL STATE	EMPTY	--	Binary	LOADED	EMPTY

¹⁾ Object Types are; Analog Input (AI), Analog Output (AO), Binary Input (BI) and Binary Output (BO).

²⁾ A single value in a column means that the value is the same in English units and in SI units.

³⁾ Point numbers that appear in brackets { } may be unbundled at the field panel.

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